ISSN 1819-6608



 $\ensuremath{\mathbb C}$ 2006 Asian Research Publishing Network (ARPN). All rights reserved.

www.arpnjournals.com

SOME EXACT SOLUTIONS OF EQUATIONS OF MOTION OF A FINITELY CONDUCTING INCOMPRESSIBLE FLUID OF VARIABLE VISCOSITY IN THE PRESENCE OF A TRANSVERSE MAGNETIC FIELD BY TRANSFORMATION METHOD

Muhammad Jamil¹ and Najeeb Alam Khan²

¹Department of Mathematics and Basic Sciences, NED University of Engineering and Technology, Karachi, Pakistan ²Department of Mathematics, University of Karachi, Karachi-75270, Pakistan E-mail: jamilned@yahoo.com

ABSTRACT

Using transformation method some exact solutions of equations of motion of a finitely conducting incompressible fluid of variable viscosity in the presence of a transverse magnetic field are determined. These solutions consist of flows for which the vorticity distribution is proportional to the stream function perturbed by a uniform stream. Streamline patterns for some of the solutions are also presented.

Keywords: equation, navier stocks, MFD, transverse, flow, viscous, fluid, magnetic field.

1. INTRODUCTION

Various methods have been used by the researchers to determine exact solutions of the Navier-Stocks equations. These methods and the exact solutions determined through these methods can be found in references [1-20] and the references their in.

Recently Naeem RK and Muhammad Jamil[21] applied transformation method to determine a class of exact solutions to flow equations of an incompressible fluid of variable viscosity in which the vorticity distribution is proportional to the stream function perturbed by a uniform stream parallel to the x-axis.

In the present work, we extend Naeem RK and Muhammad Jamil approach to determine some exact solutions of equations of motion of a finitely conducting incompressible fluid of variable viscosity in the presence of a transverse magnetic field for which the vorticity distribution is proportional to the stream function perturbed by a uniform stream inclined to the x-axis.

The plan of this paper is as follows: In section 2 basic flow equations are considered and are transformed into a new system of equations using the transformation method. In section 3, some exact solutions of the new system of equations are determined. The transformation method used in determining the exact solutions to these equations is straightforward.

2. BASIC FLOW EQUATIONS

The non-dimensional equations governing the steady motion of a finitely conducting incompressible fluid of variable viscosity, in the presence of a magnetic field from Naeem RK and Najma Tayyab[22] are:

$$\mathbf{u}_{\mathrm{X}} + \mathbf{v}_{\mathrm{Y}} + \mathbf{w}_{\mathrm{Z}} = \mathbf{0}$$

$$\begin{aligned} u \, u_x + v \, u_y + w \, u_z &= -p_x + \frac{1}{Re} \Big[(2 \, \mu \, u_x)_x + (\mu (u_y + v_x))_y + (\mu (w_x + u_z))_z \Big] \\ &+ R_H \Big[H_3 (H_{1z} - H_{3x}) - H_2 (H_{2x} - H_{1y}) \Big] \\ u \, v_x + v \, v_y + w \, v_z &= -p_y + \frac{1}{Re} \Big[(2 \, \mu \, v_y)_y + (\mu (v_z + w_y))_z + (\mu (u_y + v_x))_x \Big] \\ &+ R_H \Big[H_1 (H_{2x} - H_{1y}) - H_3 (H_{3y} - H_{2z}) \Big] \end{aligned}$$



www.arpnjournals.com

$$\begin{split} u w_{x} + v w_{y} + w w_{z} &= -p_{z} + \frac{1}{Re} \Big[(2 \mu w_{z})_{z} + (\mu (w_{x} + u_{z}))_{x} + (\mu (v_{z} + w_{y}))_{y} \Big] \\ &+ R_{H} \Big[H_{2} (H_{3y} - H_{2z}) - H_{1} (H_{1z} - H_{3x}) \Big] \\ (v H_{1} - u H_{2})_{y} - (u H_{3} - w H_{1})_{z} &= \frac{1}{R_{\sigma}} \Big(H_{1xx} + H_{1yy} + H_{1zz} \Big) \\ (w H_{2} - v H_{3})_{z} - (v H_{1} - u H_{2})_{x} &= \frac{1}{R_{\sigma}} \Big(H_{2xx} + H_{2yy} + H_{2zz} \Big) \Big] \end{split}$$

$$\left(u H_3 - w H_1 \right)_x - \left(w H_2 - v H_3 \right)_y = \frac{1}{R_\sigma} \left(H_{3xx} + H_{3yy} + H_{3zz} \right)$$

$$u T_x + v T_y + w T_z = \frac{1}{Re Pr} \left(T_{xx} + T_{yy} + T_{zz} \right) + \frac{Ec}{Re} \left[2 \mu \left(u_x^2 + v_y^2 + w_z^2 \right) + \mu \left\{ \left(v_x + u_y \right)^2 + \left(w_y + v_z \right)^2 + \left(u_z + w_x \right)^2 \right\} \right] + \frac{R_H Ec}{R_\sigma} \left[\left(H_{3y} - H_{2z} \right)^2 + \left(H_{1z} - H_{3x} \right)^2 + \left(H_{2x} - H_{1y} \right)^2 \right]$$

$$H_{1x} + H_{2y} + H_{3z} = 0$$
(1)

The meanings of various symbols used here are given in the Nomenclature. Considering the flow to be plane transverse flow, we have

$$(u, v, w) = (u, v, 0)$$

(H₁, H₂, H₃) = (0, 0, H) (2)

$$(\bullet)_{z} = 0$$

The system of Eqs.(1), utilizing Eqs.(2), becomes

$$u_x + v_y = 0 \tag{3}$$

$$u u_{x} + v u_{y} = -P_{x} + \frac{1}{Re} \left[\left(2 \mu u_{x} \right)_{x} + \left(\mu \left(u_{y} + v_{x} \right) \right)_{y} \right]$$
(4)

$$\mathbf{u} \mathbf{v}_{\mathbf{x}} + \mathbf{v} \mathbf{v}_{\mathbf{y}} = -\mathbf{P}_{\mathbf{y}} + \frac{1}{\mathrm{Re}} \left[\left(2\,\mu\,\mathbf{v}_{\mathbf{y}} \right)_{\mathbf{y}} + \left(\mu \left(\mathbf{u}_{\mathbf{y}} + \,\mathbf{v}_{\mathbf{x}} \right) \right)_{\mathbf{x}} \right]$$
(5)

$$u H_{x} + v H_{y} = \frac{1}{R_{\sigma}} \left(H_{xx} + H_{yy} \right)$$
(6)

$$u T_{x} + v T_{y} = \frac{1}{\text{Re Pr}} \left(T_{xx} + T_{yy} \right) + \frac{\text{Ec}\,\mu}{\text{Re}} \left[2 \left(u_{x}^{2} + v_{y}^{2} \right) + \left(u_{y} + v_{x} \right)^{2} \right] + \frac{R_{\text{H}} \text{Ec}}{R_{\sigma}} \left(H_{x}^{2} + H_{y}^{2} \right)$$
(7)

Where

ARPN Journal of Engineering and Applied Sciences



¢,

© 2006 Asian Research Publishing Network (ARPN). All rights reserved.

www.arpnjournals.com

$$P = p + R_{\rm H} \frac{{\rm H}^2}{2} \tag{8}$$

Equation (3) implies the existence of the stream function ψ such that

$$\mathbf{u} = \boldsymbol{\psi}_{\mathbf{y}} \quad , \quad \mathbf{v} = -\boldsymbol{\psi}_{\mathbf{x}} \tag{9}$$

The system of Eqs.(3 - 7), on utilizing Eq. (9), transform into the following system of equations

$$\psi_{x} \omega = -J_{x} + \frac{1}{Re} \Big[\mu \Big(\psi_{yy} - \psi_{xx} \Big) \Big]_{y}$$
(10)

$$\psi_{y} \omega = -J_{y} - \frac{4}{Re} \left(\mu \psi_{xy} \right)_{y} + \frac{1}{Re} \left[\mu \left(\psi_{yy} - \psi_{xx} \right) \right]_{x}$$
(11)

$$\psi_{y} H_{x} - \psi_{x} H_{y} = \frac{1}{R_{\sigma}} \left(H_{xx} + H_{yy} \right)$$
(12)

$$\psi_{y} T_{x} - \psi_{x} T_{y} = \frac{1}{\text{Re Pr}} \Big(T_{xx} + T_{yy} \Big) + \frac{\text{Ec } \mu}{\text{Re}} \Big[4 \Big(\psi_{xy} \Big)^{2} + \Big(\psi_{yy} - \psi_{xx} \Big)^{2} \Big] + \frac{\text{R}_{H} \text{Ec}}{\text{R}_{\sigma}} \Big(H_{x}^{2} + H_{y}^{2} \Big)$$
(13)

Where the vorticity function $\boldsymbol{\omega}$ and the generalized energy function J are defined by

$$\omega = -\left(\psi_{xx} + \psi_{yy}\right) \tag{14}$$

$$J = P + \frac{1}{2} \left(\psi_x^2 + \psi_y^2 \right) - \frac{2 \mu \psi_{xy}}{Re}$$
(15)

The generalized energy function J, on using Eq.(8), becomes

$$J = p + R_{\rm H} \frac{{\rm H}^2}{2} + \frac{1}{2} \left(\psi_{\rm x}^2 + \psi_{\rm y}^2 \right) - \frac{2\,\mu\,\psi_{\rm xy}}{{\rm Re}}$$
(16)

Once a solution of system of Eqs. (10-13) is determined, the pressure p is obtained from Eq. (16).

Since we are interested in the solution of the system of Eqs. (10-13) when the vorticity distribution is proportional to the stream function, perturbed by a uniform stream, we set

$$\psi_{xx} + \psi_{yy} = K \left(\psi - U x - U y \right)$$
⁽¹⁷⁾

Where $K \neq 0$ and U are real constants. On substituting

$$\Psi = \psi - \mathbf{U} \mathbf{x} - \mathbf{U} \mathbf{y} \tag{18}$$

and employing Eq.(17), the Eq. (14) becomes

$$\omega = -K\Psi$$

Equations (10) and (11), utilizing Eqs. (18) and (19), become

$$L_{x} = K U \Psi + \frac{1}{Re} \Big[\mu \Big(\Psi_{yy} - \Psi_{xx} \Big) \Big]_{y}$$
(20)

$$L_{y} = K U \Psi - \frac{4}{Re} \left(\mu \Psi_{xy} \right)_{y} + \frac{1}{Re} \left[\mu \left(\Psi_{yy} - \Psi_{xx} \right) \right]_{x}$$
(21)

Where

(19)



www.arpnjournals.com

$$L = J - \frac{K\Psi^2}{2}$$

 $L_{xy} = L_{yx}$, provide Equations (20) and (21), on using the integrability condition

$$M_{xx} - M_{yy} - \frac{4}{Re} \left(\mu \Psi_{xy} \right)_{xy} + K U \left(\Psi_x - \Psi_y \right) = 0$$
(22)
Where
$$M = \frac{\mu \left(\Psi_{yy} - \Psi_{xx} \right)}{R}$$

$$M = \frac{\mu \left(\Psi_{yy} - \Psi_{xx} \right)}{Re}$$

Equation (22) is the equation that must be satisfied by the function Ψ and the viscosity μ for the motion of a finitely conducting incompressible fluid of variable viscosity in the presence of a transverse magnetic field in which the vorticity distribution is proportional to the stream function ψ perturbed by a uniform stream inclined to the x-axis. Equation (12) and (13), employing Eq. (18), become

$$\left(\Psi_{y}+U\right)H_{x}-\left(\Psi_{x}+U\right)H_{y}=\frac{1}{R_{\sigma}}\left(H_{xx}+H_{yy}\right)$$
(23)

$$\left(\Psi_{y} + U\right) T_{x} - \left(\Psi_{x} + U\right) T_{y} = \frac{1}{\operatorname{Re}\operatorname{Pr}} \left(T_{xx} + T_{yy}\right) + \frac{\operatorname{Ec} \mu}{\operatorname{Re}} \left[4\left(\psi_{xy}\right)^{2} + \left(\psi_{yy} - \psi_{xx}\right)^{2}\right] + \frac{\operatorname{R}_{H}\operatorname{Ec}}{\operatorname{R}_{\sigma}} \left(\operatorname{H}_{x}^{2} + \operatorname{H}_{y}^{2}\right)$$

$$(24)$$

Let us now determine the solutions of the system of Eqs. (22 - 24) in the next section.

3. SOLUTIONS

In this section we determine some exact solutions of the system of Eqs. (22 - 24) as follows: Equation (17), employing Eq.(18), becomes

$$\nabla^2 \Psi = K \Psi \tag{25}$$

Plane wave solution of the Helmholtz Eq. (25) exists in the form

 $\Psi(\mathbf{x},\mathbf{y}) = \mathbf{N}(\xi)$ (26)Where

 $\xi = \left(x\cos\theta + y\sin\theta\right) , \qquad -\pi \le \theta < \pi$

Equation (25), on using Eq. (26), yields

$$N''(\xi) - K N(\xi) = 0$$
(28)

Equation (28) possesses solutions for the following cases:

Case-I :	Κ	$= -n^2$,	n > 0
Case-1:	K	$= -n^{-}$,	n > 0

Case-II: $K = m^2$ m > 0

We now consider these cases separately and also determine the solutions of Eqs. (22-24) for these cases as follows: Our strategy is that first we find the function $\Psi(x, y)$ from Eqs. (26) and (28), and use this Ψ to determine μ , H and T from system of Eqs.(22-24).

CASE-I:

For this case the solution of Eq. (28) is given by

$$N(\xi) = A_1(\theta) \cos(n \xi + A_2(\theta))$$

(29)

(27)



(32)

© 2006 Asian Research Publishing Network (ARPN). All rights reserved.

www.arpnjournals.com

Where

 $\xi = \left(x \cos \theta + y \sin \theta \right) \quad , \qquad -\pi \le \theta < \pi$

and $A_1(\theta)$ and $A_2(\theta)$ are real constants dependent on the parameter θ , and $-\pi \le \theta < \pi$. The function $\Psi(x, y)$, therefore is given by

$$\Psi = A_1(\theta) \cos(n(x\cos\theta + y\sin\theta) + A_2(\theta))$$
(30)

Equation (22), utilizing Eq. (30), becomes

 $Z_{\eta\eta} = A_3(\theta) \sin\eta \tag{31}$

Where

 $Z = \mu \cos \eta$

$$\eta = n\xi + B(\theta) \tag{33}$$

$$A_3(\theta) = \frac{\operatorname{Re} K \cup (\cos \theta - \sin \theta)}{n^3}$$

The solution of Eq. (31) is

$$Z = -A_3(\theta) \sin\eta + A_4(\theta) \eta + A_5(\theta)$$
(34)

Where $A_4(\theta)$ and $A_5(\theta)$ are real constants dependent on the parameter θ , and $-\pi \le \theta < \pi$. Equations (32) and (34) give

$$\mu = -A_3(\theta) \tan \eta + A_4(\theta) \eta \sec \eta + A_5(\theta) \sec \eta$$
(35)

Equation (23), utilizing Eq. (30), becomes

$$H_{\eta\eta} - A_6(\theta) H_{\eta} = 0 \tag{36}$$

Where

$$A_{6}(\theta) = \frac{R_{\sigma} U (\cos \theta - \sin \theta)}{n}$$

 $\eta = n \xi + A_2(\theta)$

The solution of Eq. (36) is

$$H = A_7(\theta) e^{A_6(\theta)\eta} + A_8(\theta)$$
(37)

Where $A_7(\theta)$ and $A_8(\theta)$ are real constants dependent on the parameter θ , and $-\pi \le \theta < \pi$. Equation (25), using Eqs. (30), (33), (35) and (37), becomes

$$T_{\eta\eta} + A_9(\theta) T_{\eta} = -2 A_{10}(\theta) \sin 2\eta + A_{11}(\theta) \eta \cos \eta + A_{12}(\theta) \cos \eta + A_{13}(\theta) e^{2A_6(\theta)\eta}$$
(38)

Where

$$A_{9}(\theta) = -\frac{U \operatorname{Re} \operatorname{Pr} (\cos \theta - \sin \theta)}{n}$$
$$A_{10}(\theta) = -\frac{K U \operatorname{Re} \operatorname{Pr} \operatorname{Ec} A_{1}^{2}(\theta) (\cos \theta - \sin \theta)}{4n}$$



¢,

©2006 Asian Research Publishing Network (ARPN). All rights reserved.

www.arpnjournals.com

$$A_{11}(\theta) = -n^2 \operatorname{Pr} \operatorname{Ec} A_1(\theta) A_4(\theta)$$

$$A_{12}(\theta) = -n^2 \operatorname{Pr} \operatorname{Ec} A_1(\theta) A_5(\theta)$$

$$A_{13}(\theta) = \frac{\text{Re Pr Ec } R_{\text{H}} A_{6}^{2}(\theta) A_{7}^{2}(\theta)}{R_{\sigma}}$$

The solution of Eq. (38) is

 $T = A_{14}(\theta) (2\sin 2\eta + A_9(\theta) \cos 2\eta) + A_{15}(\theta) (\sin \eta + A_9(\theta) \cos \eta) + A_{16} (A_9(\theta) \sin \eta - \cos \eta)$

+
$$A_{17}(\theta) \eta (A_9(\theta) \sin \eta - \cos \eta) + A_{18}(\theta) e^{2A6(\theta)\eta} + A_{19}(\theta) e^{-A9(\theta)\eta} + A_{20}(\theta)$$
 (39)

Where

 $\eta = n\xi + A_2(\theta)$

$$A_{14}(\theta) = \frac{A_{10}(\theta)}{4 + A_9^2(\theta)}$$

$$A_{15}(\theta) = \frac{A_{11}(\theta)}{1 + A_9^2(\theta)} + \frac{A_{11}(\theta)}{(1 + A_9^2(\theta))^2}$$

$$A_{16}(\theta) = \frac{A_{12}(\theta)}{1 + A_9^2(\theta)} - \frac{A_9(\theta)A_{11}(\theta)}{(1 + A_9^2(\theta))^2}$$

$$A_{17}(\theta) = \frac{A_{11}(\theta)}{1 + A_9^2(\theta)}$$

$$A_{18}(\theta) = \frac{A_{13}(\theta)}{2A_6(\theta)(2 + A_9(\theta))}$$

Where $A_{19}(\theta)$ and $A_{20}(\theta)$ are real constants dependent on the parameter θ , and $-\pi \le \theta < \pi$. The exact solutions of system of Eqs. (22-24), in this case is given by

$$\begin{split} \mu &= -A_3(\theta)\tan\eta + A_4(\theta)\eta \ \text{sec}\eta + A_5(\theta) \ \text{sec}\eta \\ H &= A_7(\theta)e^{A_6(\theta)\eta} + A_8(\theta) \\ T &= A_{14}(\theta)(2\sin2\eta + A_9(\theta)\cos2\eta) + A_{15}(\theta) \ (\sin\eta + A_9(\theta)\cos\eta) + A_{16} \ (A_9(\theta)\sin\eta - \cos\eta) \\ &+ A_{17}(\theta) \ \eta (A_9(\theta)\sin\eta - \cos\eta) + A_{18}(\theta) \ e^{2A_6(\theta)\eta} + A_{19}(\theta) \ e^{-A_9(\theta)\eta} + A_{20}(\theta) \end{split}$$

The stream function ψ for this case is given by

$$\psi = U(x+y) + A_1(\theta) \cos(n(x\cos\theta + y\sin\theta) + A_2(\theta))$$
(40)

It represent a uniform stream U in the positive x direction plus a perturbation that is periodic in x and y. Some typical streamline patterns are given in Figures (1 - 4).





 $\ensuremath{\textcircled{\sc 0}}$ 2006 Asian Research Publishing Network (ARPN). All rights reserved.

www.arpnjournals.com

CASE-II:

For this case

$$N(\xi) = B_1(\theta) e^{m\xi} + B_2(\theta)(\theta) e^{-m\xi}$$

Where $B_1(\theta)$ and $B_2(\theta)$ are real constants dependent on the parameter θ , and $-\pi \le \theta < \pi$. The function $\Psi(x, y)$, therefore is given by

$$\Psi(\xi) = B_1(\theta) e^{m\xi} + B_2(\theta)(\theta) e^{-m\xi}$$
(41)

Equations (22), utilizing Eqs. (41), becomes

$$G_{\xi\xi} = m^2 B_3(\theta) e^{m\xi} + m^2 B_4(\theta) e^{-m\xi}$$

$$\tag{42}$$

Where

$$G = \mu \Psi \tag{43}$$

$$B_{3}(\theta) = \frac{K \ U \ \text{Re} \ B_{1}(\theta) \ (\cos\theta - \sin\theta)}{m^{3}}$$

$$B_4(\theta) = -\frac{K \ U \ \text{Re} \ B_2(\theta) (\cos\theta - \sin\theta)}{m^3}$$

The solution of Eq. (42) is

$$G = B_3(\theta) e^{m\xi} + B_4(\theta) e^{-m\xi} + B_5(\theta) \xi + B_6(\theta)$$

$$(44)$$

Where $B_5(\theta)$ and $B_6(\theta)$ are real constants dependent on the parameter θ , and $-\pi \le \theta < \pi$. Equation (44), on using Eqs. (41) and (43) give

$$\mu = \frac{B_3(\theta) e^{m\xi} + B_4(\theta) e^{-m\xi} + B_5(\theta) \xi + B_6(\theta)}{B_1(\theta) e^{m\xi} + B_2(\theta) e^{-m\xi}}$$
(45)

Equation (23), utilizing Eqs. (41) ,becomes

$$H_{\xi\xi} - B_7(\theta) H_{\xi} = 0$$
(46)
Where

 $\xi = \left(x \cos \theta + y \sin \theta \right) \quad , \qquad -\pi \le \theta < \pi$

$$B_7(\theta) = R_{\sigma} U (\cos \theta - \sin \theta)$$

The solution of Eq. (46) is

$$H = B_8(\theta) e^{B_7(\theta)\xi} + B_9(\theta)$$
(47)

Where $B_8(\theta)$ and $B_9(\theta)$ are real constants dependent on the parameter θ , and $-\pi \le \theta < \pi$.

Equation (25), using Eqs.(27), (41),(45) and (47), becomes

$$T_{\xi\xi} + B_{10}(\theta) T_{\xi} = -\Pr Ec m^{4} G \Psi + B_{11}(\theta) e^{2B7(\theta)\xi}$$
(48)

Where



www.arpnjournals.com

$$B_{10}(\theta) = -\operatorname{Re}\operatorname{Pr} U \left(\cos\theta - \sin\theta\right)$$

$$B_{11}(\theta) = \frac{\text{Re Pr Ec } R_{\text{H}} B_7^2(\theta) B_8^2(\theta)}{R_{\sigma}}$$

The solution of Eqs. (48) is

$$T = -\Pr \ Ec \ m^4 \ \left[\ B_{12}(\theta) \ e^{2m\xi} \ + \ B_{13}(\theta) \ e^{-2m\xi} \ + \ B_{14}(\theta) \ \xi \ e^{m\xi} \ + B_{15}(\theta) \ \xi \ e^{-m\xi} \ + \ B_{16}(\theta) \ e^{m\xi} \right]$$

+
$$B_{17}(\theta)e^{-m\xi} + B_{18}(\theta)(\xi - 1)] + B_{19}(\theta)e^{2B_7(\theta)\xi} + B_{20}(\theta)e^{-B_{11}(\theta)\xi} + B_{21}(\theta)$$
 (49)

Where

$$\begin{split} \xi &= \left(x \cos\theta + y \sin\theta \right) \quad , \qquad -\pi \le \theta < \pi \\ B_{12}(\theta) &= \frac{B_{1}(\theta) B_{3}(\theta)}{2m \left(2m + B_{10}(\theta) \right)} \\ B_{13}(\theta) &= \frac{B_{2}(\theta) B_{4}(\theta)}{2m \left(2m - B_{10}(\theta) \right)} \\ B_{13}(\theta) &= \frac{B_{1}(\theta) B_{5}(\theta)}{m \left(m + B_{10}(\theta) \right)} \\ B_{14}(\theta) &= \frac{B_{1}(\theta) B_{5}(\theta)}{m \left(m - B_{10}(\theta) \right)} \\ B_{15}(\theta) &= \frac{B_{2}(\theta) B_{5}(\theta)}{m \left(m - B_{10}(\theta) \right)} \\ B_{16}(\theta) &= \frac{B_{1}(\theta) B_{6}(\theta)}{m \left(m + B_{10}(\theta) \right)} - \frac{B_{1}(\theta) B_{5}(\theta)}{m^{2} \left(m + B_{10}(\theta) \right)} - \frac{B_{1}(\theta) B_{5}(\theta)}{m \left(m + B_{10}(\theta) \right)^{2}} \\ B_{17}(\theta) &= \frac{B_{2}(\theta) B_{6}(\theta)}{m \left(m - B_{10}(\theta) \right)} + \frac{B_{2}(\theta) B_{5}(\theta)}{m^{2} \left(m - B_{10}(\theta) \right)} + \frac{B_{2}(\theta) B_{5}(\theta)}{m \left(m + B_{10}(\theta) \right)^{2}} \\ B_{18}(\theta) &= \frac{B_{1}(\theta) B_{4}(\theta) + B_{2}(\theta) B_{3}(\theta)}{B_{10}(\theta)} \end{split}$$

$$B_{19}(\theta) = \frac{B_{11}(\theta)}{2 B_7(\theta) (2 B_7(\theta) + B_{10}(\theta))}$$

Where $B_{20}(\theta)$ and $B_{21}(\theta)$ are real constants dependent on the parameter θ , and $-\pi \le \theta < \pi$. The exact solutions of system of Eqs.(5-10), in this case is given by

$$\mu = \frac{B_3(\theta) e^{m\xi} + B_4(\theta) e^{-m\xi} + B_5(\theta) \xi + B_6(\theta)}{B_1(\theta) e^{m\xi} + B_2(\theta) e^{-m\xi}}$$

 $H = B_8(\theta) e^{B7(\theta)\xi} + B_9(\theta)$

ARPN Journal of Engineering and Applied Sciences



¢,

(50)

© 2006 Asian Research Publishing Network (ARPN). All rights reserved.

www.arpnjournals.com

$$T = -\Pr \operatorname{Ec} m^{4} \left[B_{12}(\theta) e^{2m\xi} + B_{13}(\theta) e^{-2m\xi} + B_{14}(\theta) \xi e^{m\xi} + B_{15}(\theta) \xi e^{-m\xi} + B_{16}(\theta) e^{m\xi} + B_{17}(\theta) e^{-m\xi} + B_{18}(\theta) (\xi - 1) \right] + B_{19}(\theta) e^{2B7(\theta)\xi} + B_{20}(\theta) e^{-B11(\theta)\xi} + B_{21}(\theta)$$

For this case the stream function

$$\psi = U(x + y) + B_1(\theta) e^{m(x \cos\theta + y \sin\theta)} + B_2(\theta) e^{-m(x \cos\theta + y \sin\theta)}$$

represents a uniform stream U in the positive x direction plus a perturbation that is not periodic in x and y. Some typical streamline patterns are given in Figures (5-10).

If in particular we assume K = 0, then the solution of Eq. (21) is

$$N(\xi) = C_1(\theta) \xi + C_2(\theta) , \qquad -\pi \le \theta < \pi$$

Where $C_1(\theta)$ and $C_2(\theta)$ are real constants dependent on the parameter θ , and $-\pi \le \theta < \pi$. The function $\Psi(x, y)$, therefore is given by

$$\Psi = C_1(\theta) \xi + C_2(\theta)$$
(51)

When K = 0, Eq. (22) is identically satisfied and therefore the viscosity μ is arbitrary and Eq. (23) provides the same solution as in case-II, that is

$$H = C_4(\theta) e^{C_3(\theta)\xi} + C_5(\theta)$$
(52)

Where $C_4(\theta)$ and $C_5(\theta)$ are real constants dependent on the parameter θ , and $-\pi \le \theta < \pi$. Employing Eqs. (51) and (52) in Eq. (24), we get

$$T_{\xi\xi} - U \operatorname{Re} \operatorname{Pr} \left(\cos\theta - \sin\theta \right) T_{\xi} = \frac{\operatorname{Re} \operatorname{Pr} \operatorname{R}_{\mathrm{H}} \operatorname{Ec} \operatorname{C_{3}}^{2}(\theta) \operatorname{C_{4}}^{2}(\theta)}{\operatorname{R}_{\sigma}}$$
(53)

The solution of Eq. (53) is

 $\langle \rangle$

$$T = \frac{R_{\rm H} \operatorname{Ec} C_3^{\ 2}(\theta) C_4^{\ 2}(\theta)}{U R_{\sigma} (\cos\theta - \sin\theta)} \xi + C_8(\theta) e^{C_6(\theta)\xi} + C_9(\theta)$$
(54)

Where

 $\xi \,=\, \left(\,x\,\cos\theta \,+\, y\,\sin\theta\,\,\right) \quad, \qquad -\,\pi \leq \theta < \pi \label{eq:eq:expansion}$

and $C_8(\theta)$ and $C_9(\theta)$ are real constants dependent on the parameter θ , and $-\pi \le \theta < \pi$. The exact solutions of system of Eqs. (22-24), in this case is given by

 μ is arbitrary

$$H = C_4(\theta) e^{C_3(\theta) \xi} + C_5(\theta)$$

$$T = \frac{R_H \operatorname{Ec} C_3^2(\theta) C_4^2(\theta)}{U R_\sigma (\cos\theta - \sin\theta)} \xi + C_8(\theta) e^{C_6(\theta)\xi} + C_9(\theta)$$



 $\ensuremath{\textcircled{O}}$ 2006 Asian Research Publishing Network (ARPN). All rights reserved.

www.arpnjournals.com

K = 0, corresponds to an irrotational flow and it is the following uniform flow

 $\Psi = (U + C_1(\theta)\cos\theta)x + (U + C_1(\theta)\sin\theta)y + C_2(\theta)$

4. CONCLUSIONS

Some exact solutions of equations of motion of a finitely conducting incompressible fluid of variable viscosity in the presence of a transverse magnetic field are determined, using transformation method. These solutions consist of flows for which the vorticity distribution is proportional to the stream function perturbed by a uniform stream. Streamline patterns for some of the solutions are also presented. By assigning different values to the constants there in the solutions, we can generate more streamline patterns.

REFERENCES

Hui W. H. 1987. Exact solutions of the unsteady twodimensional Navier-Stokes equations. Journal of Applied Mathematics and Physics. Vol. 38, pp. 689-702.

Kovasznay L. I. G. 1948. Laminar flow behind a twodimensional grid. Proc Cambridge Phil. Soc. 44, pp. 58-62.

Wang C. Y. 1989. Exact solutions of the unsteady Navier-Stokes equations. Appl. Mech. Rev. Vol. 42, No. 11, part 2, pp. s269-s282.

Naeem R. K. 1994. Exact solutions of flow equations of an incompressible fluid of variable viscosity via oneparameter group. The Arabian Journal for Science and Engineering. Vol.19, No.1, pp. 111-114.

Naeem R. K. and Nadeem S. A.1996. Study of plane steady flows of an incompressible fluid of variable viscosity using Martins Method. Applied Mechanics and Engineering. Vol. 1, No. 3, pp. 397-433.

Naeem R. K. and Ali S. A. 2001. A Class of exact solutions to equations governing the steady plane flows of an incompressible fluid of variable viscosity via von- Mises variables. International Journal of Applied Mechanics and Engineering. Vol. 6, No. 2, pp. 395-436.

Naeem R. K. and Ali S. S. 1994. Exact solutions of the equations of motion of an incompressible fluid of variable viscosity. Karachi University Journal of science. Vol. 22 (1&2), pp. 97-100.

Taylor G. I. 1923. On the decay of vortices in a viscous fluid. Phil. Mag. 46, pp. 671-674.

Siddique J. I. 2001. Unsteady flow of viscous fluid by transformation method. M. Phil dissertation, Department of Mathematics, Quaid-e-Azam University, Islamabad.

Biosvert R. E., Ames W. F. and Srivastava. 1983. U.N. Group properties and new solutions of Navier- Stockes equations. J. of Engg. Math. Vol. 17, pp. 203-221.

Morgan G. W. 1950. A study of motion in a rotating liquid. Proc. Royal, Society, A, Vol. 206, pp. 108-130.

Chandna O. P., Murgai A. and Rankin G. W. 1983. A steady rational plane gas flow problem by Hodograph method. Int. J. Engg. Sci.. Vol. 21, No. 12, pp. 1443-1449.

Chandna O. P. and Smith A. C. 1971. Some steady plane compressible flows. J. de Mechanique. Vol.10, pp. 15-325.

Baron R. M. and O. P. Chandna. 1981. Hodograph transformations and solutions in constantly inclined MHD plane flows. J. Engineering Mathematics. Vol. 15, pp. 220-221.

Chandna O. P.and M. R. Grag. 1976. Steady transverse MHD viscous flows. Canadian J. of Physics. Vol. 54, pp. 262-267.

Gundersen R. 1966. Steady Two-Dimensional Magnetohydrodynamics Flows. ZAMP. Vol. 17, pp. 6-12.

Nath V. I. and O. P. Chandna. 1973. On plane Transverse MHD flows Tensor. N.S., 27, pp. 27-32.

Nath V. I. 1974. On plane flows of compressible fluid. Institute Lombarodo (Rend. Sc.) A108. pp. 458-476.

Prim R. C. 1952. Steady rotational flow of ideal gases. Journal of Rational Mechanics and Analysis. 1. pp. 425-497.

Prim R. and Nemenyi P. 1948. On the motion of prim gases. J. Math. Phys. Vol. 27, pp. 130-135.

Naeem R. K. and Muhammad Jamil. 2005. A class of exact solutions of an incompressible fluid of variable viscosity. Quaid-E-Awam University Research Journal of Engineering, Science & Technology. Vol. 6, No.1&2, pp. 11-18.

Naeem R. K. and Najma Tayyab. 1997. Some exact solutions of equations of motion of a finitely conducting incompressible fluid of variable viscosity in the presence of a transverse magnetic field via One-Parameter Group. Karachi University Journal of science. Vol. 25 (1&2), pp. 1-9.

Naeem R. K. and Jawed A. 1996. Some exact solutions of motion of an inviscid compressible fluid via one-parameter group. Pak. J. Sci. Ind. Res. Vol.39, pp. 5-8.

(55)



www.arpnjournals.com

Swaminathan M. K., O. P. Chandna and K. Sridhar. 1983. Hodograph study of transverse Magnetohydrodynamics flows. Canadian J. of Physics. Vol. 61, pp. 1050-1055.

Lin S. P. and Tobak M. 1986. Reversed flow above a plate with suction. AIAAJ. Vol. 24, pp. 334-335.

NOMENCLATURE

u, v, w		non-dimensional velocity component
H_1, H_2, H_3		non-dimensional components of the magnetic field vector ${f H}$
Н	—	non-dimensional transverse components of the magnetic field vector H
р		non-dimensional pressure
Т		non-dimensional temperature
μ		viscosity of the fluid
Re		Reynolds number
R _H		magnetic pressure number
R _σ		magnetic Reynolds number
Pr		Prandtl number
Ec		Eckert number
Ψ		stream function
J		generalized energy function
ω		vorticity function
Ψ, L, M, N, Z, H, G, P		functions
<i>x</i> , <i>y</i> ,ξ,η, θ		variables
K, U, m, n		real constants
$A_1(\theta), \dots, A_{20}(\theta)$	_	real constants dependent on the parameter $\ \theta$, and – $\pi \leq \theta < \pi$.
$B_1(\theta), \dots, B_{21}(\theta)$		real constants dependent on the parameter θ , and $-\pi \leq \theta < \pi$.
$C_1(\theta), \ldots, C_9(\theta)$		real constants dependent on the parameter θ , and $-\pi \leq \theta < \pi$.

Subscripts

<i>x, y, z, xx, yy</i>	 differentiation with respect to cartesian coordinates x and y
ξ, η, ξξ, ηη	 differentiation with respect to ξ and η .

Superscripts

" ____ differentiation with respect to the argument.

Bansal J. L. 1984. Viscous Fluid dynamics. Oxford and IBH Publishing Co. New Delhi.



(

© 2006 Asian Research Publishing Network (ARPN). All rights reserved.



Figure-1. Streamline pattern for $\cos\left(\frac{\sqrt{3}}{2}x + \frac{1}{2}y\right) + x + y = \text{constant}$



Figure-2. Streamline pattern for $7 \cos\left(\frac{1}{2}x - \frac{\sqrt{3}}{2}y - 1\right) + x + y = \text{constant}$





Figure-3. Streamline pattern for $-6 \cos\left(\frac{\sqrt{3}}{2}x + \frac{1}{2}y\right) + 0.6(x + y) = \text{constant}$



¢,

© 2006 Asian Research Publishing Network (ARPN). All rights reserved.



Figure-4. Streamline pattern for
$$-3\cos\left(\frac{\sqrt{3}}{2}x - \frac{1}{2}y\right) + x + y = \text{constant}$$







Figure-5. Streamline pattern for $\operatorname{Cosh}\left(\frac{1}{2}x - \frac{\sqrt{3}}{2}y\right) + 2(x + y) = \operatorname{constant}$





Figure-6. Streamline pattern for $\cosh(0.819x - 0.574y) + 0.2(x + y) = \text{constant}$









¢,

© 2006 Asian Research Publishing Network (ARPN). All rights reserved.



Figure-8. Streamline pattern for $\sinh\left(\frac{1}{2}x - \frac{\sqrt{3}}{2}y\right) + 5(x + y) = \text{constant}$





Figure-9. Streamline pattern for $\sinh\left(0.61\left(\frac{x-y}{\sqrt{2}}\right)\right) - (x + y) = \text{constant}$







Figure-10. Streamline pattern for $\operatorname{Exp}\left(-\frac{\sqrt{3}}{2}x + \frac{1}{2}y\right) - \operatorname{Exp}\left(-\left(-\frac{\sqrt{3}}{2}x + \frac{1}{2}y\right)\right) - (x + y) = \text{constant}$